

**THIS PAPER MUST NOT BE REMOVED  
FROM THE EXAMINATION ROOM**

**STUDENT NAME:  
STUDENT NUMBER:**

**Internal Students Only**

# **THE UNIVERSITY OF QUEENSLAND**

**School of Information Technology  
& Electrical Engineering**

Final Examination – 2013

**ELEC 3004 / 7312:**

Systems: Signals & Controls

**(Formula Sheet)**

**CLOSED BOOK**

**TIME: One Hundred and Seventy Five (175) minutes for working**

**Five (5) minutes for perusal before examination begins**

**ANSWER ALL QUESTIONS ON SHEET PROVIDED**

**QUESTIONS CARRY THE NUMBER OF MARKS INDICATED**

**Drawing instruments and one battery-operated or solar-powered electronic calculator may be used but NO pre-programmed material or calculator instruction booklets are allowed in the examination room.**

**ELEC 3004 / 7312: Systems: Signals & Controls**  
**Final Examination – 2013**

Table 1: Commonly used Formulae

The Laplace Transform

$$F(s) = \int_0^{\infty} f(t)e^{-st} dt$$

The  $\mathcal{Z}$  Transform

$$F(z) = \sum_{n=0}^{\infty} f[n]z^{-n}$$

IIR Filter Pre-warp

$$\omega_a = \frac{2}{\Delta t} \tan\left(\frac{\omega_d \Delta t}{2}\right)$$

Bi-linear Transform

$$s = \frac{2(1 - z^{-1})}{\Delta t(1 + z^{-1})}$$

FIR Filter Coefficients

$$c_n = \frac{\Delta t}{\pi} \int_0^{\pi/\Delta t} H_d(\omega) \cos(n\omega\Delta t) d\omega$$

Table 2: Comparison of Fourier representations.

<b>Time Domain</b>	<b>Periodic</b>	<b>Non-periodic</b>	
<b>Discrete</b>	<b>Discrete Fourier Transform</b> $\tilde{X}[k] = \frac{1}{N} \sum_{n=0}^{N-1} \tilde{x}[n]e^{-j2\pi kn/N}$ $\tilde{x}[n] = \sum_{k=0}^{N-1} \tilde{X}[k]e^{j2\pi kn/N}$	<b>Discrete-Time Fourier Transform</b> $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n]e^{-j\omega n}$ $x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega})e^{j\omega n} d\omega$	<b>Periodic</b>
<b>Continuous</b>	<b>Complex Fourier Series</b> $X[k] = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t)e^{-j2\pi kt/T} dt$ $\tilde{x}(t) = \sum_{k=-\infty}^{\infty} X[k]e^{j2\pi kt/T}$	<b>Fourier Transform</b> $X(j\omega) = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$ $x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega)e^{j\omega t} d\omega$	<b>Non-periodic Freq. Domain</b>
	<b>Discrete</b>	<b>Continuous</b>	

**ELEC 3004 / 7312: Systems: Signals & Controls**  
**Final Examination – 2013**

Table 3: Selected Fourier, Laplace and  $z$ -transform pairs.

Signal	$\longleftrightarrow$	Transform	ROC
$\tilde{x}[n] = \sum_{p=-\infty}^{\infty} \delta[n - pN]$	$\xleftrightarrow{DFT}$	$\tilde{X}[k] = \frac{1}{N}$	
$x[n] = \delta[n]$	$\xleftrightarrow{DTFT}$	$X(e^{j\omega}) = 1$	
$\tilde{x}(t) = \sum_{p=-\infty}^{\infty} \delta(t - pT)$	$\xleftrightarrow{FS}$	$X[k] = \frac{1}{T}$	
$\delta_T[t] = \sum_{p=-\infty}^{\infty} \delta(t - pT)$	$\xleftrightarrow{FT}$	$X(j\omega) = \frac{2\pi}{T} \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_0)$	
$\cos(\omega_0 t)$	$\xleftrightarrow{FT}$	$X(j\omega) = \pi\delta(\omega - \omega_0) + \pi\delta(\omega + \omega_0)$	
$\sin(\omega_0 t)$	$\xleftrightarrow{FT}$	$X(j\omega) = j\pi\delta(\omega + \omega_0) - j\pi\delta(\omega - \omega_0)$	
$x(t) = \begin{cases} 1 & \text{when }  t  \leq T_0, \\ 0 & \text{otherwise.} \end{cases}$	$\xleftrightarrow{FT}$	$X(j\omega) = \frac{2\sin(\omega T_0)}{\omega}$	
$x(t) = \frac{1}{\pi t} \sin(\omega_c t)$	$\xleftrightarrow{FT}$	$X(j\omega) = \begin{cases} 1 & \text{when }  \omega  \leq  \omega_c , \\ 0 & \text{otherwise.} \end{cases}$	
$x(t) = \delta(t)$	$\xleftrightarrow{FT}$	$X(j\omega) = 1$	
$x(t) = \delta(t - t_0)$	$\xleftrightarrow{FT}$	$X(j\omega) = e^{-j\omega t_0}$	
$x(t) = u(t)$	$\xleftrightarrow{FT}$	$X(j\omega) = \pi\delta(\omega) + \frac{1}{j\omega}$	
$x[n] = \frac{\omega_c}{\pi} \text{sinc } \omega_c n$	$\xleftrightarrow{DTFT}$	$X(e^{j\omega}) = \begin{cases} 1 & \text{when }  \omega  <  \omega_c , \\ 0 & \text{otherwise.} \end{cases}$	
$x(t) = \delta(t)$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = 1$	all $s$
(unit step) $x(t) = u(t)$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = \frac{1}{s}$	
(unit ramp) $x(t) = t$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = \frac{1}{s^2}$	
$x(t) = \sin(s_0 t)$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = \frac{s_0}{(s^2 + s_0^2)}$	
$x(t) = \cos(s_0 t)$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = \frac{s}{(s^2 + s_0^2)}$	
$x(t) = e^{s_0 t} u(t)$	$\xleftrightarrow{\mathcal{L}}$	$X(s) = \frac{1}{s - s_0}$	$\Re\{s\} > \Re\{s_0\}$
$x[n] = \delta[n]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = 1$	all $z$
$x[n] = \delta[n - m]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = z^{-m}$	
$x[n] = u[n]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = \frac{z}{z - 1}$	
$x[n] = z_0^n u[n]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = \frac{1}{1 - z_0 z^{-1}}$	$ z  >  z_0 $
$x[n] = -z_0^n u[-n - 1]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = \frac{1}{1 - z_0 z^{-1}}$	$ z  <  z_0 $
$x[n] = a^n u[n]$	$\xleftrightarrow{\mathcal{Z}}$	$X(z) = \frac{z}{z - a}$	$ z  <  a $

**ELEC 3004 / 7312: Systems: Signals & Controls**  
**Final Examination – 2013**

Table 4: Properties of the Discrete-time Fourier Transform.

Property	Time domain	Frequency domain
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(e^{j\omega}) + bX_2(e^{j\omega})$
Differentiation (frequency)	$nx[n]$	$j \frac{dX(e^{j\omega})}{d\omega}$
Time-shift	$x[n - n_0]$	$e^{-j\omega n_0} X(e^{j\omega})$
Frequency-shift	$e^{j\omega_0 n} x[n]$	$X(e^{j(\omega - \omega_0)})$
Convolution	$x_1[n] * x_2[n]$	$X_1(e^{j\omega}) X_2(e^{j\omega})$
Modulation	$x_1[n] x_2[n]$	$\frac{1}{2\pi} X_1(e^{j\omega}) \otimes X_2(e^{j\omega})$
Time-reversal	$x[-n]$	$X(e^{-j\omega})$
Conjugation	$x^*[n]$	$X^*(e^{-j\omega})$
Symmetry (real)	$\Im\{x[n]\} = 0$	$X(e^{j\omega}) = X^*(e^{-j\omega})$
Symmetry (imag)	$\Re\{x[n]\} = 0$	$X(e^{j\omega}) = -X^*(e^{-j\omega})$
Parseval	$\sum_{n=-\infty}^{\infty}  x[n] ^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi}  X(e^{j\omega}) ^2 d\omega$	

Table 5: Properties of the Fourier series.

Property	Time domain	Frequency domain
Linearity	$a\tilde{x}_1(t) + b\tilde{x}_2(t)$	$aX_1[k] + bX_2[k]$
Differentiation (time)	$\frac{d\tilde{x}(t)}{dt}$	$\frac{j2\pi k}{T} X[k]$
Time-shift	$\tilde{x}(t - t_0)$	$e^{-j2\pi k t_0 / T} X[k]$
Frequency-shift	$e^{j2\pi k_0 t / T} \tilde{x}(t)$	$X[k - k_0]$
Convolution	$\tilde{x}_1(t) \otimes \tilde{x}_2(t)$	$T X_1[k] X_2[k]$
Modulation	$\tilde{x}_1(t) \tilde{x}_2(t)$	$X_1[k] * X_2[k]$
Time-reversal	$\tilde{x}(-t)$	$X[-k]$
Conjugation	$\tilde{x}^*(t)$	$X^*[-k]$
Symmetry (real)	$\Im\{\tilde{x}(t)\} = 0$	$X[k] = X^*[-k]$
Symmetry (imag)	$\Re\{\tilde{x}(t)\} = 0$	$X[k] = -X^*[-k]$
Parseval	$\frac{1}{T} \int_{-T/2}^{T/2}  \tilde{x}(t) ^2 dt = \sum_{k=-\infty}^{\infty}  X[k] ^2$	

**ELEC 3004 / 7312: Systems: Signals & Controls**  
**Final Examination – 2013**

Table 6: Properties of the Fourier transform.

Property	Time domain	Frequency domain
Linearity	$a\tilde{x}_1(t) + b\tilde{x}_2(t)$	$aX_1(j\omega) + bX_2(j\omega)$
Duality	$X(jt)$	$2\pi x(-\omega)$
Differentiation	$\frac{dx(t)}{dt}$	$j\omega X(j\omega)$
Integration	$\int_{-\infty}^t x(\tau) d\tau$	$\frac{1}{j\omega} X(j\omega) + \pi X(j0)\delta(\omega)$
Time-shift	$x(t - t_0)$	$e^{-j\omega t_0} X(j\omega)$
Frequency-shift	$e^{j\omega_0 t} x(t)$	$X(j(\omega - \omega_0))$
Convolution	$x_1(t) * x_2(t)$	$X_1(j\omega)X_2(j\omega)$
Modulation	$x_1(t)x_2(t)$	$\frac{1}{2\pi} X_1(j\omega) * X_2(j\omega)$
Time-reversal	$x(-t)$	$X(-j\omega)$
Conjugation	$x^*(t)$	$X^*(-j\omega)$
Symmetry (real)	$\Im\{x(t)\} = 0$	$X(j\omega) = X^*(-j\omega)$
Symmetry (imag)	$\Re\{x(t)\} = 0$	$X(j\omega) = -X^*(-j\omega)$
Scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{j\omega}{a}\right)$
Parseval	$\int_{-\infty}^{\infty}  x(t) ^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty}  X(j\omega) ^2 d\omega$	

Table 7: Properties of the  $z$ -transform.

Property	Time domain	$z$ -domain	ROC
Linearity	$ax_1[n] + bx_2[n]$	$aX_1(z) + bX_2(z)$	$\subseteq R_{x_1} \cap R_{x_2}$
Time-shift	$x[n - n_0]$	$z^{-n_0} X(z)$	$R_x^\dagger$
Scaling in $z$	$z_0^n x[n]$	$X(z/z_0)$	$ z_0  R_x$
Differentiation in $z$	$nx[n]$	$-z \frac{dX(z)}{dz}$	$R_x^\dagger$
Time-reversal	$x[-n]$	$X(1/z)$	$1/R_x$
Conjugation	$x^*[n]$	$X^*(z^*)$	$R_x$
Symmetry (real)	$\Im\{x[n]\} = 0$	$X(z) = X^*(z^*)$	
Symmetry (imag)	$\Re\{X[n]\} = 0$	$X(z) = -X^*(z^*)$	
Convolution	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	$\subseteq R_{x_1} \cap R_{x_2}$
Initial value	$x[n] = 0, n < 0 \Rightarrow x[0] = \lim_{z \rightarrow \infty} X(z)$		

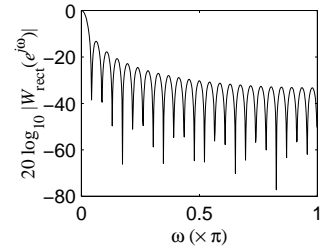
<sup>†</sup>  $z = 0$  or  $z = \infty$  may have been added or removed from the ROC.

**ELEC 3004 / 7312: Systems: Signals & Controls**  
**Final Examination – 2013**

Table 8: Commonly used window functions.

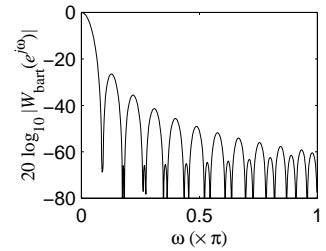
*Rectangular:*

$$w_{\text{rect}}[n] = \begin{cases} 1 & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



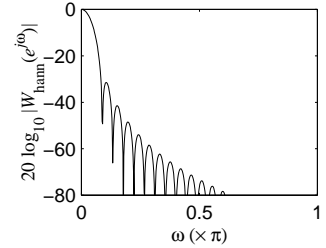
*Bartlett (triangular):*

$$w_{\text{bart}}[n] = \begin{cases} 2n/M & \text{when } 0 \leq n \leq M/2, \\ 2 - 2n/M & \text{when } M/2 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



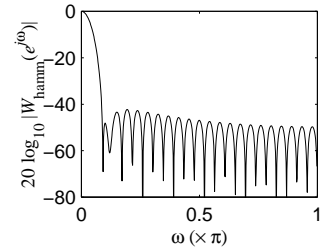
*Hanning:*

$$w_{\text{hann}}[n] = \begin{cases} \frac{1}{2} - \frac{1}{2} \cos(2\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



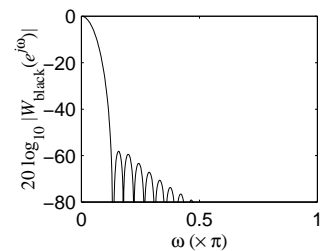
*Hamming:*

$$w_{\text{hamm}}[n] = \begin{cases} 0.54 - 0.46 \cos(2\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



*Blackman:*

$$w_{\text{black}}[n] = \begin{cases} 0.42 - 0.5 \cos(2\pi n/M) \\ \quad + 0.08 \cos(4\pi n/M) & \text{when } 0 \leq n \leq M, \\ 0 & \text{otherwise.} \end{cases}$$



Type of Window	Peak Side-Lobe Amplitude (Relative; dB)	Approximate Width of Main Lobe	Peak Approximation Error, $20 \log_{10} \delta$ (dB)
Rectangular	-13	$4\pi/(M+1)$	-21
Bartlett	-25	$8\pi/M$	-25
Hanning	-31	$8\pi/M$	-44
Hamming	-41	$8\pi/M$	-53
Blackman	-57	$12\pi/M$	-74