## METR 4202 Sensing Lab Demonstration Assessment

Team №		Team Name:			Date:	6 / Octobe	er / 2016	
Member 1	]	Member 2	Member 3	Membe	er 4	Meml	per 5	
		Dice (Number of st	anding dominos):					
Grading Process	<ul> <li>Dice<sub>1</sub> (Number of standing dominos):</li> <li>Dice<sub>2</sub> (Amount of clutter &amp; Number of landscape dominos):</li> </ul>							
Band Overview: (from Demo Criteria)	• () • () • ()	<ul> <li>Grade 3-4 (45%-65%): Calibration works → basic operation (3-6 claps or 33-50/75)</li> <li>Grade 5 (65%-75%): Intermediate operation (≥6 claps or 50-59/75)</li> <li>Grade 6 (75%-85%): Good performance. Challenge attempted (≥12 claps or ~60-64/75)</li> </ul>						
	$\checkmark$		Core Tasks			Claps	Score	
		Camera Calibration						
		Sensor Placement						
Functional		Object Detection					4	
Tasks		Object Mapping					4	
		Motion Tracking					4	
		Challenge 1:						
		Challenge 2:					/75	
	1	Cursory operation						
Form	3	Some consideration						
(Sub-Band)	6	Design and impleme	entation are <b>very good</b>					
	10		entation are outstanding				/10	
Methodological Explanation	Team can explain the robot's operation (Judges Discretion, may include bonus marks for creative implementations)							
	<u> </u>							
							/15	
				Total Mark:			/100	
Summary								

More	
Comments	
Marker Name:	