RWTH Toolbox and NXT condensed installation guide

Complete instructions at this link (skip installing Matlab of course):
http://www.clemson.edu/ces/departments/ece/document_resource/undergrad/matlab/RWTH_Setup.pdf

These have video, but appear to skip the crucial bit about "libusb-win32":
http://people.clemson.edu/~nwatts/engr141/instructions/

Once you've done it the before, these are the condensed instructions (i.e. they have little pieces left out that you'll remember after the first time):

1. Download and unzip: http://www.mindstorms.rwth-aachen.de/documents/downloads/RWTHMindstormsNXTv4.07.zip

2. In Matlab, browse to this folder. Right-click -> Add to path -> This and Subfolders (this is temporary, a more permanent way is in the other instruction pages)

3. Outside the lab, you will have to install the NXT Drivers from here: http://mindstorms.lego.com/en-us/support/files/Driver.aspx

4. *This step only needs to be done once to get the RWTH program on the brick*
   a. *Download: http://bricxcc.sourceforge.net/nextexplorer.zip and run it.*
   b. *Find the "MotorControl2.rxe" file and upload it to the brick.*

5. Download and unzip: http://sourceforge.net/projects/libusb-win32/files/ and click through the dialogs. Install the ".ini".

6. In Matlab, you should always follow this process:
   a. >> h = COM_OpenNX();
   b. >> COM_SetDefaultNXT(h);
   c. >> ... Do stuff here ...
   d. >> COM_CloseNXT(COM_GetDefaultNXT());

7. Documentation found here: http://www.mindstorms.rwth-aachen.de/trac/wiki/Documentation